

# **EZ-3 Timer Control Board**

PN: 27558

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## DESCRIPTION

Prop builders have long used three-stage timers for simple props and effects. The problem with traditional products is the inability to modify behavior beyond the original design. The EZ-3 Timer Control Board solves this problem by converting the [re]programmable Prop-1, Prop-2, and Prop-SX controllers into simple or advanced 3-stage timing control devices.

## **PRODUCT APPLICATIONS**

- Props and holiday displays
- Special FX

# **FEATURES & BENEFITS**

- Built-in potentiometer circuits to allow for trigger delay, on time, and off (reset) time
- Colored LEDs indicate timing stages
- Built-in manual switch for testing
- Terminal block provides for connection of external (N.O.) trigger device
- Pre-configured for Prop-1; may optionally be configured for the Prop-2 and Prop-SX
- Compact size: 1.5" x 2" (38.1mm x 50.8mm)

## Mounting the EZ-3

Mount the EZ-3 by mating the 3x8 female socket with the 3x8 TTL header on the Prop-1, Prop-2, or Prop-SX. Secure the EZ-3 to the controller using a stand-off and screws (provided).

## **ULN2x03 Modification**

The EZ-3 includes three potentiometer circuits that must be freed from the inputs of the ULN2x03 output driver used for valves and solenoids connected to the OUTx terminals. Modification of the ULN2x03 is best handled with a small diagonal cutter. Remove the pins as shown below.

Serial I/O (P7) Trigger (P6) Delay (P5) On Time (P4) Off Time (P3)	ULN280	ULN200	
	303	2003	ב ב

ULN2803: Remove pins 1 through 5 ULN2003: Remove pins 1 through 4

# **Reconfiguring for the Prop-2/Prop-SX**

The potentiometer circuits on the EZ-3 are pre-configured for the POT instruction used by the Prop-1 controller. To reconfigure for the RCTIME instruction used by the Prop-2 and Prop-SX you must bridge the "solder jumpers" with solder. Using a low-wattage (25W) soldering iron and rosin-core solder bridge each of the solder jumpers; all six jumpers must be bridged for proper operation.



**CAUTION**: Use caution when adding solder to the solder bridges on the EZ-3 as excessive heat can damage the PCB. Use a low-wattage iron and just enough solder to make a connection between the inner pad and outer ring. Using acid-core solder <u>will</u> damage the PCB.

# Triggering

The EZ-3 – with the correct firmware in the prop controller – can be triggered thusly:

- 1. Press the MAN TR (manual trigger) button
- 2. Connect a N.O. button or switch (e.g., mat switch) to the EXT TR (external trigger) terminal block
- 3. Connect a N.O. or active-high device (e.g., PIR sensor) to the TRIG header (P6)

EFX-TEK recommends that the input on P6 be debounced to prevent false triggering on a spurious input. See the demonstration program at the end of this document for an example of input debouncing.

## **MECHANICAL SPECIFICATIONS**





#### Accessories

 805-00035
 14" Extension Cable

 805-00175
 68" Extension Cable

## **Additional Applications**

For additional ideas and application notes for the EZ-3 Timer Control Board be sure to visit us on the Internet at the following links:

www.efx-tek.com forums.efx-tek.com

#### Errata

#### **Demonstration Program**

The following Prop-1 program allows the EZ-3 to control a standard, 3-stage timer application. The trigger delay time may be set from zero to 10 seconds, the on time from 1 to 60 seconds, and the off time from 1 to 20 seconds.

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**NOTE**: If you'd like custom timing for a 3-stage application using the EZ-3 simply post a programming request with details in our Tech Support forums.

```
1_____
.
   File..... EZ-3 Standard.BS1
1
  Purpose...
.
  Author.... EFX-TEK
            Copyright (c) 2009 EFX-TEK
           Some Rights Reserved
            -- see http://creativecommons.org/licenses/by/3.0/
  E-mail.... teamefx@efx-tek.com
   Started...
   Updated... 01 MAR 2009
   {$STAMP BS1}
   {$PBASIC 1.0}
 _____
' ----- [ Program Description ]-----
' Standard 3-stage timer application.
' Trigger Delay... 0 TO 10 seconds
' On Time..... 1 TO 60 seconds
' Off Timer..... 1 TO 20 seconds
' For best accuracy of each stage you should run the POT Scaling program
 from the Run menu for each stage. Set the scale value into the POT
' instruction for each stage.
' Trigger Delay... Pin 5
' On Time..... Pin 4
' Off Timer.... Pin 3
' Turn each pot fully clockwise and use the scale value provided. The
' scale value will be around 100 but will vary from pot-to-pot based on
' minor component differences.
' ----- [ Revision History ]-----
' -----[ I/O Definitions ]------
                   = 7
SYMBOL Sio
                                        ' SETUP = out; no ULN
SYMBOL Trigger
                                        ' SETUP = DN
                  = PIN6
SYMBOL AdjTrDelay
                   = 5
                                        ' on delay (no ULN)
SYMBOL AdjOnTime
                                        ' run time (no ULN)
                   = 4
                                        ' off delay (no ULN)
SYMBOL AdjOffTime
                   = 3
                                        ' trigger delay output
SYMBOL TrDelay
                   = PIN2
SYMBOL OnTime
                   = PIN1
                                        ' on time output
SYMBOL OffTime
                                        ' off time output
                   = PINO
```

```
' -----[ Constants ]-----
                                         _____
SYMBOL IsOn
                    = 1
                                          ' for active-high in/out
SYMBOL ISOFF
                    = 0
SYMBOL Yes
                    = 1
SYMBOL No
                     = 0
' -----[ Variables ]------
SYMBOL negFlag = BT
                   = BIT15
SYMBOL tix
                    = W1
' -----[ Initialization ]------
Reset:
 PINS = %00000000
                                          ' clear all
 DIRS = %00000111
                                          ' set outputs
' -----[ Program Code ]------
Main:
 timer = 0
                                          ' reset timer
Check Trigger:
                                          ' debounce input
 PAUSE 5
                                          ' loop pad
                                          ' update timer
 timer = timer + 5 * Trigger
 IF timer < 100 THEN Check Trigger
                                          ' wait for 0.1 sec input
' Trigger delay is 0 to 10 seconds
' -- convert pot span (0 to 250) to 0 to 100 "tix"
' -- tix = timer x 0.4
Trigger Delay:
 POT AdjTrDelay, 100, timer
                                          ' raw input, 5 to 255
 timer = timer - 5
                                          ' correct low end offset
 IF negFlag = No THEN Run TD
  timer = 0
                                          ' fix roll-under
Run TD:
 IF timer = 0 THEN On Time
                                          ' skip if zero
 tix = timer ** $6666
                                          ' tix = timer x 0.4
 TrDelay = IsOn
 GOSUB Delay Tix
 TrDelay = IsOff
' On time is 1 to 60 seconds
' -- convert pot span (0 to 250) to 10 to 600 "tix"
' -- tix = (timer x 2.36) + 10
On Time:
 \overline{timer} = 0
 POT AdjOnTime, 100, timer
 timer = timer - 5
 IF negFlag = No THEN Run OT
  timer = 0
Run OT:
tix = timer * 2
                                      ' tix = timer x 2
```

```
timer = timer ** $5C28
                                             ' x 0.36
 tix = tix + timer
                                             ' tix = timer x 2.36
 tix = tix + 10
                                             ' set low end
 OnTime = IsOn
 GOSUB Delay Tix
 OnTime = IsOff
' Off time is 1 to 20 seconds
' -- convert pot span (0 to 250) to 10 to 200 "tix"
-- tix = (timer x 0.76) + 10
Off Time:
 timer = 0
 POT AdjOffTime, 100, timer
 timer = timer - 5
 IF negFlag = No THEN Run_XT
   timer = 0
Run XT:
 tix = timer ** $C28F
                                             'tix = timer x 0.75
 tix = tix + 10
                                             ' set low end
 OffTime = IsOn
 GOSUB Delay Tix
 OffTime = IsOff
 GOTO Main
' -----[ Subroutines ]-----
' Delay in 0.1-second units
' -- put delay in "tix" before calling
Delay Tix:
 IF tix = 0 THEN DT Exit
   PAUSE 100
   tix = tix - 1
  GOTO Delay Tix
DT Exit:
RETURN
```